

Structured Adiabatic Quantum Search

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Abstract

We examine the use of adiabatic quantum algorithms to solve structured, or nested, search problems. We construct suitable time dependent Hamiltonians and derive the computation times for a general class of nested searches involving n qubits. As expected, we find that as additional structure is included, the Hamiltonians become more local and the computation times decrease.

1 Introduction

Adiabatic Quantum Computation (AQC) is a relatively new paradigm in the field of quantum computing. Whereas in the standard model of QC (SQC), an algorithm is defined as a sequence of discrete unitary transformations, AQC (see, e.g., [1, 2, 3, 4, 5, 6]) considers the continuous time evolution of the quantum system, described by the Schrödinger equation

$$i\frac{d}{dt}|\Psi(t)\rangle = H(t)|\Psi(t)\rangle \quad (1)$$

with a time dependent Hamiltonian $H(t)$. A computational problem which has been studied extensively in both SQC and AQC is the unstructured search. In its simplest form the unstructured search corresponds to finding a single marked state (needle) in a completely unstructured database (haystack) of N states. In the case that the physical system consists of n two state particles (qubits), $N = 2^n$ corresponds to the size of the complete Hilbert space for the system. Classically a random search of N objects requires on average N operations to pick out the marked object. It was shown by BBBV [7] that for SQC, the lower bound on the corresponding number of steps is of order \sqrt{N} . Grover was the first to construct a specific QC algorithm that achieved this lower bound [8].

In the context of AQC, the physical quantity that seems to most closely correspond to the number of steps of a SQC algorithm is the time required to do the computation. It is therefore not surprising that under fairly standard assumptions, it can be shown that the time required for the unstructured search in AQC increases as \sqrt{N} ¹.

In many physical systems, it is possible to use additional structure in order to shorten the search. For example, consider a database of items with n distinguishable bits. A maximally structured classical search would check one bit at a time in order to find the correct marked state. Such a search would require $O(n)$ operations. The key is that, by using the existing structure, one is able in principle to search n two-dimensional objects, instead of a random search among $N = 2^n$ objects.

The above example is a special case of a general class of nested searches, which have recently been analyzed [9] in the context of SQC. The purpose of the present paper is to study structured *adiabatic* quantum search. We find that additional structure shortens the running time and makes the Hamiltonian more local (concerning the interactions of the system, as is explained below). Our results for the running time are consistent with the conjecture (cf. [9]) that (adiabatic) quantum computation improves the running time of the corresponding classical algorithm by a square root; due to the fact that quantum computation manipulates probability amplitudes, whose squares give the corresponding probabilities.

We start with a short description of AQC in general. In Section 3 we show that the unstructured search studied by Grover leads to a spatially non-local Hamiltonian when considered in the conventional model for the

¹In a dynamical quantum system one can always shorten the time by increasing the energy. The consequences for AQC of increasing the energy temporarily have recently been analyzed in [11].

implementation of quantum algorithms, namely two-level quantum systems (qubits), such as spin-1/2 particles. That is, the unstructured adiabatic search requires an n -body interaction for an n -qubit system. In Section 4, we define the notion of a structured adiabatic quantum search Hamiltonian and show that it is in general local, in the sense referred to above: it couples only a subset of the total number of qubits. We then start our detailed analysis of nested searches with the most intuitive case, the maximally structured search, and consider its adiabatic evolution and running time, which is shown to scale as $T = O(\sqrt{n})$. Finally, we study the general case and obtain its running time, comparing different ways of structuring the system.

2 Adiabatic Quantum Computation

The method of AQC is based on the use of the adiabatic theorem for considering quantum computing as continuous time evolution from some easily prepared initial state $|\psi_i\rangle$ to a final state $|\psi_f\rangle$ that encodes the solution to the computational problem. Specifically, the adiabatic theorem (see, e.g. [10]) states the following: a system which is described by a time-dependent Hamiltonian $H(t)$ will stay close to the instantaneous ground state of $H(t)$ provided that the time evolution is slow enough. In quantitative terms, after time T

$$|\langle E_0; T | \Psi(T) \rangle|^2 \geq 1 - \epsilon^2, \quad (2)$$

where E_0 is the lowest energy eigenvalue and $\epsilon \ll 1$, provided that:

$$\frac{|\langle E_1; t | \frac{dH}{dt} | E_0; t \rangle|}{\omega_{min}^2} \leq \epsilon \quad (3)$$

where

$$\omega_{min} = \min_{0 \leq t \leq T} [E_1(t) - E_0(t)] \quad (4)$$

is the minimum gap between the lowest two energy eigenvalues E_0 and E_1 . Thus, if (3) is satisfied, a measurement after time T gives as result the solution with almost certainty, i.e. with probability $\approx 1 - \epsilon^2$.

The time-dependent Hamiltonian that is traditionally used in AQC is constructed as the linear combination

$$H(t) = f(t) H_i + g(t) H_f \quad (5)$$

where $|\psi_i\rangle$, $|\psi_f\rangle$ are the ground states of H_i , H_f , respectively and $f(t)$ and $g(t)$ are usually considered to be monotonic functions such that $f(0) = 1$, $f(T) = 0$, $g(0) = 0$ and $g(T) = 1$, where T is the total computation time.

It will be useful for what follows to note that the adiabatic theorem (3) can be modified [12] for the case of an m -fold degenerate first excited state. In this case, it reads

$$\sum_{i=1}^m \frac{|\langle E_1 | \frac{dH}{dt} | E_0 \rangle_i|^2}{\omega_{min}^4} \leq \epsilon^2. \quad (6)$$

3 Unstructured search in AQC

The goal of the search algorithm is to find a marked object $|m\rangle$ in an unstructured database of size N in as few steps as possible. Classically, one has to look at $O(N)$ objects to find the marked one. One advantage of the quantum search is that it manipulates the amplitude of the marked state, leading to a quadratic amplification of the probability. The initial state is the superposition of all states with equal weight,

$$|\Psi_0\rangle \equiv |\Psi(0)\rangle = \sum_{i=1}^N \frac{1}{\sqrt{N}} |i\rangle. \quad (7)$$

A natural choice for a Hamiltonian that has this state as its ground state is:

$$H_i = 1 - |\Psi_0\rangle\langle\Psi_0|. \quad (8)$$

Correspondingly one must choose (cf. Section 4.1),

$$H_f = 1 - |m\rangle\langle m|, \quad (9)$$

which has the ground state $|m\rangle$. H_f is in a sense the adiabatic analogue of the “oracle” $\hat{I} - 2|m\rangle\langle m|$ used in the Grover search algorithm. It projects out the marked state $|m\rangle$. Thus, in the framework of AQC, the initial state $|\Psi_0\rangle$ evolves into $|m\rangle$ in time T , given that the Hamiltonian (5) varies slowly enough with time. In the simplest case [1] $f(t) = 1 - t/T$ and $g(t) = t/T$, the minimum running time increases with N at the same rate as for the classical search: $T = O(N)$. However, one can improve this by choosing $f(t)$ and $g(t)$ to vary most rapidly when the gap ω is the largest. For example, one can use the approach of [2], in which $f(t) = 1 - s(t)$, $g(t) = s(t)$ with $s(0) = 0$ and $s(T) = 1$. This choice yields an adiabaticity condition of the form:

$$\frac{|\langle E_1; s | \frac{dH(s)}{ds} | E_0; s \rangle|}{\omega^2(s)} \left| \frac{ds}{dt} \right| \leq \epsilon. \quad (10)$$

One is then free to choose $s(t)$ so that the bound in (10) is saturated for all t . This yields a running time $T = O(\sqrt{N})$. Recently, it was shown [11] that

with a more general choice of the functions f and g in the construction of $H(t)$ the running time can – in principle – be made independent of N , but at the cost of requiring a large amount of energy to be *temporarily* injected into the system.

We are now lead to the question of how to implement a generic AQC algorithm in a real quantum computer, and what kind of physical systems might be suitable. The conventional scheme for the implementation of quantum computation considers a system of uncorrelated 2-level quantum systems (qubits), e.g. spin 1/2-particles. The 1-qubit space \mathcal{H}_i is spanned by $|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$. The n -qubit space is given by the tensor product

$$\mathcal{H} = \mathcal{H}_1 \otimes \mathcal{H}_2 \otimes \dots \otimes \mathcal{H}_n \quad (11)$$

with the basis $\{|\alpha_1, \dots, \alpha_n\rangle = |\alpha_1\rangle \otimes \dots \otimes |\alpha_n\rangle | \alpha_i \in \{0, 1\}\}$. The marked state is $|m\rangle = |z_1 \dots z_n\rangle = |z_1\rangle \otimes \dots \otimes |z_n\rangle$ with $z_i \in \{0, 1\}$. In this framework, the final Hamiltonian

$$H_f = 1 - |m\rangle\langle m| \quad (12)$$

can be written in terms of Pauli spin matrices

$$H_f = 1 - \prod_{i=1}^n \left(\frac{1}{2} (1 - (-1)^{z_i} \sigma_z^{(i)}) \right) \quad (13)$$

$$\equiv \sum_{i=0}^n c_i \prod_{j=0}^i \sigma_z^{(j)}. \quad (14)$$

In this form it is clear that the Hamiltonian contains a product of n spin matrices, which implies interactions among all qubits. This non-locality may put constraints on possible implementations of such algorithms, at least for spin systems².

In the next section, we describe how, by using additional structure, the search can be modified to reduce the spatial non-locality in the Hamiltonian, while keeping the initial and final ground state the same. This structured search also provides a shorter computation time than the unstructured one.

4 Structured adiabatic search

The adiabatic theorem requires the evolution of the quantum system to be slow enough to keep the system in its ground state for all times. It seems

²If one considers AQC only as a possible simulation of SQC, the non-locality is irrelevant.

plausible that it is “easier” for the system to stay in its ground state if there are no long range interactions, but only 2 or 3-qubit interactions. In order to find a Hamiltonian that realizes this idea, it is useful to consider the problem in the language of decision clauses etc.(cf. [1]):

4.1 Satisfiability problems, clauses and Hamiltonians

Search algorithms belong to the class of satisfiability problems. A satisfiability problem is a combination of decision clauses C_i which have an element of $\{0, 1\}$ (true or false) as output which depends on the values of some set of the qubits of the system. A formula is an n -bit instance of satisfiability,

$$F \equiv C_1 \wedge C_2 \wedge \dots \wedge C_m, \quad (15)$$

i.e. in general m clauses acting on n bits. The action of a clause or formula on an assignment can be translated into the action of a Hamiltonian on the states of a physical system (up to an overall factor): Formula (15) is mapped into

$$H(t) = H_1(t) + H_2(t) + \dots + H_m(t), \quad (16)$$

where each H_i is constructed from the clause C_i and acts only on the bits of this clause. For example, if C_i is a two-bit clause, H_i contains only operators that act on these two bits, it can have at most a two-body interaction term. The action of H_i on the bits absent in C_i is given by the identity operator. The initial state is the ground state of $H(0)$, and the ground state of $H(t = T)$ satisfies all the clauses in the formula.

In this language, the unstructured search algorithm is a single clause that acts on n qubits and has a unique (but unknown) satisfying assignment, $|m\rangle$.

It should be noted that the form of H_f given in (9) is the most general one available for an oracle search. By definition, an oracle clause acts as

$$C_m(|m\rangle) = 0 \quad (17)$$

$$C_m(|i\rangle) = 1 \quad \forall i \neq m. \quad (18)$$

The corresponding adiabatic Hamiltonian must therefore fulfill

$$H(t = T)|m\rangle = H_f|m\rangle = 0 \quad (19)$$

$$H(t = T)|i\rangle = H_f|i\rangle = f(T)|i\rangle \quad \forall i \neq m, \quad (20)$$

where $f(T)$ should be the same for all $i \neq m$. Therefore, H_f is diagonal, and it reads

$$\begin{aligned} H_f &= f(T) \sum_{i \neq m} |i\rangle\langle i| \\ &= f(T)[1 - |m\rangle\langle m|]. \end{aligned} \quad (21)$$

4.2 Maximally structured search

The unstructured search, which is non-local in space, corresponds to a single n -bit clause. In order to find a local Hamiltonian, it is therefore the most intuitive alternative to consider a formula of n 1-bit clauses,

$$F = C_1 \wedge C_2 \wedge \dots \wedge C_n, \quad (22)$$

where C_i is satisfied if and only if the i -th bit has the required value z_i for the marked state $|m\rangle = |z_1 z_2 \dots z_n\rangle$. We call this “maximally structured” because it corresponds to the maximal splitting of the system: The adiabatic Hamiltonian which has as ground state the unique satisfying assignment of F is a sum of 1-bit versions of the oracle Hamiltonian,

$$H_f^{str} = \sum_{i=1}^n h_i \quad (23)$$

with

$$\begin{aligned} h_i &= 1 \otimes \dots \otimes 1 \otimes (1 - |z_i\rangle\langle z_i|) \otimes 1 \otimes \dots \otimes 1 \\ &= 1 \otimes \dots \otimes 1 \otimes \left[\frac{1}{2}(1 - (-1)^{z_i} \sigma_z) \right] \otimes 1 \otimes \dots \otimes 1 \\ &\equiv \frac{1}{2}(1 - (-1)^{z_i} \sigma_z^{(i)}), \end{aligned} \quad (24)$$

which act as oracle on the i -th bit and as identity on the others. The application of H_f^{str} on a general state $|\alpha_1 \alpha_2 \dots \alpha_n\rangle$ gives the number of qubits with $\alpha_i \neq z_i$. This illustrates the crucial difference between this procedure and the unstructured search. The latter leads to the same answer, 1, for all unsatisfying assignments, whereas in the present case the query gives the number $F[|\alpha\rangle]$ of unsatisfied clauses. Thus, one gets additional information.

As before, the initial state $|\Psi_0\rangle$ is the ground state of $H_i = 1 - |\Psi_0\rangle\langle\Psi_0|$, which can be written as

$$H_i^{str} \equiv \frac{1}{2} \sum_{i=1}^n (1 - \sigma_x^{(i)}). \quad (25)$$

After some algebra (cf. [12]), the eigenvalues of the Hamiltonian

$$H^{str}(t) = \frac{1}{2} f(s) \sum_{i=1}^n (1 - \sigma_x^{(i)}) + \frac{1}{2} g(s) \sum_{i=1}^n (1 - (-1)^{z_i} \sigma_z^{(i)}) \quad (26)$$

are found to be

$$E_m^{str} = \frac{n}{2}(f + g) - m\sqrt{f^2 + g^2} \quad (27)$$

where $m = \sum m_i$, with $m_i = \pm 1/2$ representing the spin up and down of the i -th particle, corresponding to $\alpha_i = 0, 1$. The ground state is obtained for $m_i = 1/2 \forall i$, i.e. $m = n/2$. The first excited state ($m = n/2 - 1$) is n -fold degenerate. The crucial condition for the adiabatic theorem to hold is a non-vanishing gap between the ground state and the first excited state, which is fulfilled:

$$\omega \equiv E_1^{str} - E_0^{str} = \sqrt{f^2 + g^2} \neq 0. \quad (28)$$

Note that this result corresponds to Eq.(14) of [11] for $2^n = N = 2$, i.e. for $n = 1$, the single qubit adiabatic search. The running time is determined by the adiabatic theorem, which in the case of a degenerate first excited state leads to the condition (6). The transition probability to each of the first excited states is proportional to the square of

$${}_i\langle E_1^{str} | \frac{dH}{dt} | E_0^{str} \rangle = -\frac{(-1)^{z_i}}{2} \frac{\dot{f}g - \dot{g}f}{\sqrt{f^2 + g^2}}, \quad (29)$$

so the total transition probability is n times Eq.(29) squared (cf. Eq.(15) in [11] for $N = 2$). For an estimate of the running time, we consider the simplest case in which f and g are linear in s , $f(s) = 1 - s(t)$ and $g(s) = s(t)$, which, after optimizing $s(t)$ as in the previous section, results in (cf.[12])

$$T = \sqrt{n}/\epsilon = \sqrt{\log N}/\epsilon, \quad (30)$$

polynomial in n . It should be noted that a similar polynomial time algorithm has been studied in [1].

4.3 General case of structured search

The transformation of the n -bit clause into n 1-bit clauses is not the only possibility of introducing structure to the search. For example, one could also consider clauses acting on 2 qubits,

$$F_2 = C_{12} \wedge C_{34} \wedge \dots \wedge C_{(n-1)n} \quad (31)$$

corresponding to the Hamiltonian

$$H_f^{str2} = \sum_{i=0}^{n/2-1} h_{[2i+1][2(i+1)]}, \quad (32)$$

where

$$h_{[2i+1][2(i+1)]} = 1 \otimes \dots \otimes 1 \otimes (1 - |z_{2i+1} z_{2(i+1)}\rangle \langle z_{2i+1} z_{2(i+1)}|) \otimes 1 \otimes \dots \otimes 1 \quad (33)$$

m	n/m	ϵT	α	β
1	6	7.94	0.9962	∞
2	3	3.74	0.9518	3.8074
3	2	3.00	0.8842	2.0000
6	1	2.45	0.7211	1.0000

Table 1: Comparison of times for various splittings for $n = 6$.

m	n/m	ϵT	α	β
1	30	32768.00	1.0000	∞
2	15	256.00	1.0000	16.0000
3	10	55.40	0.9999	7.3084
5	6	17.75	0.9973	3.5743
6	5	13.64	0.9940	2.9165
10	3	8.37	0.9695	1.8451
15	2	6.71	0.9297	1.4057
30	1	5.48	0.8307	1.0000

Table 2: Comparison of times for various splittings for $n = 30$.

acts on the two neighboring qubits as oracle and as identity on the others.

A more interesting case with respect to realization would be

$$H_f = \sum_{i=1}^{n-1} h_{i[i+1]}, \quad (34)$$

with overlap of the interacting qubit-pairs (see the discussion in [12]).

In general, any splitting of the $N = 2^n$ -dimensional Hilbert space into m smaller spaces of dimensions $N_i = 2^{n_i}$ with $\sum n_i = n$ is possible. In order to compare the effects of different ways of splitting, we calculate the running time for several cases numerically (cf. [11] for the method).

In order to investigate the scaling of T with the splitting, we define the two coefficients α, β implicitly by:

$$\begin{aligned} \epsilon T &= (\sqrt{m} \sqrt{2^{n/m}})^\alpha \\ \epsilon T &= (\sqrt{m})^\beta. \end{aligned} \quad (35)$$

We find (see Tables 1 and 2) that for no splitting ($m = 1$), $\alpha \rightarrow 1$ for large n , which means the running time is $T = O(\sqrt{N})$, as is known from the unstructured search.

For $m = 2$, i.e. $n = n_1 + n_2$, the time is shortened, and the optimal value in this case is achieved for $n_1 = n_2$.

For $m \geq 2$, the running time is even shorter, and it scales with the root of the dimension of the largest Hilbert space of the splitting, so it is again optimal for equal values of n_i for all i . This can also be seen from the expression for the running time,

$$T = \frac{1}{\epsilon} \int_0^1 ds |\dot{f}g - \dot{g}f| \sqrt{\sum_{i=1}^m \frac{N_i - 1}{N_i^2} \frac{1}{\omega_i^6}} \quad (36)$$

with

$$\omega_i = \sqrt{(f - g)^2 + \frac{4}{N_i} fg} \quad (37)$$

the gap for the i -th subsystem. For splitting into m parts of equal size, $N_i = 2^{n/m} \forall i$, and Eq.(36) simplifies to

$$T = \frac{1}{\epsilon} \sqrt{m} \frac{\sqrt{N_i - 1}}{N_i} \int_0^1 ds \frac{|\dot{f}g - \dot{g}f|}{[(f - g)^2 + \frac{4}{N_i} fg]^{3/2}} \quad (38)$$

(which reduces to Eq.(20) in [11] for $m = 1$) where the integral scales with N_i . For $n/m \gg 1$, we find $\alpha \sim 1$, and

$$\epsilon T = \sqrt{m} \sqrt{2^{n/m}}. \quad (39)$$

For maximal splitting, $m = n$ and $n_i = 1 \forall i$, leading to $\beta = 1$, which results in $T = O(\sqrt{n})$, as shown above.

5 Conclusions

We have shown how additional structure affects both the running time and locality of the Hamiltonian required for an adiabatic quantum search algorithm. As expected, the more structure, the more local the Hamiltonian and the shorter the running time. In fact, the expressions we have obtained for the running time of the general structured search suggest strongly that adiabatic quantum computation consistently improves the running time for the corresponding classical algorithm by a square root. This supports the conjecture (cf. [9]) that the speed-up achieved by quantum computation can be directly attributed to the fact that the quantum computation algorithm manipulates probability amplitudes, whose squares give the corresponding probabilities. It would be interesting to see whether this conjecture can be

proven in more general contexts. Another interesting topic for future work concerns what happens in the more general case that the pairwise interactions overlap. These and other related issues will be addressed elsewhere.

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